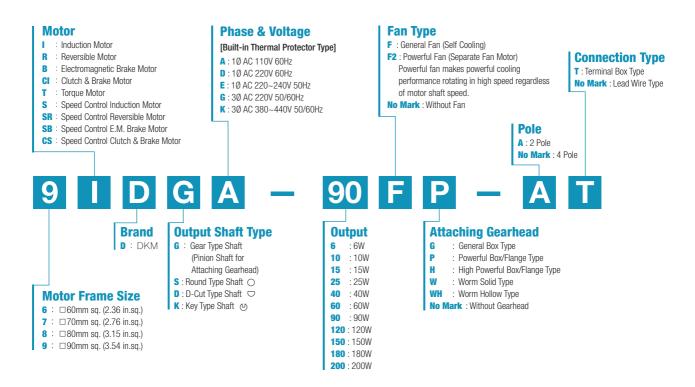


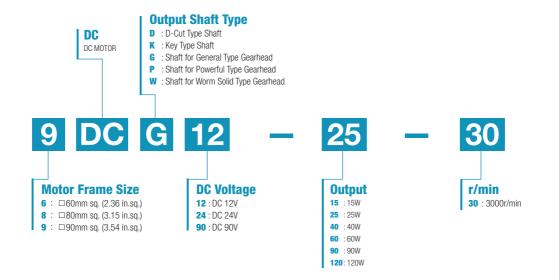
Information

Product Coding System

AC Motors

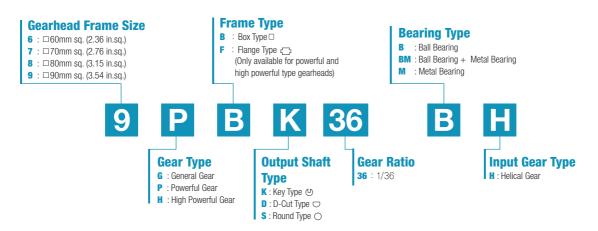


O DC Motors

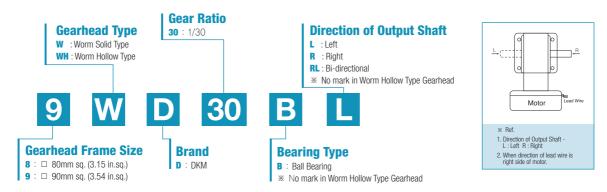




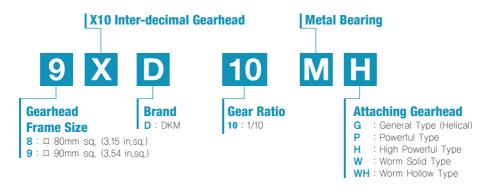
Parallel Gearhead



Worm Gearhead



Inter-decimal Gearhead



In case of requiring high gear reduction ratio that cannot be generated by single gearhead, please use Inter-decimal gearhead with general gearhead. And please be advised that in this case only revolution speed of output shaft will reduce by 10:1 without increasing of maximum permissible torque.

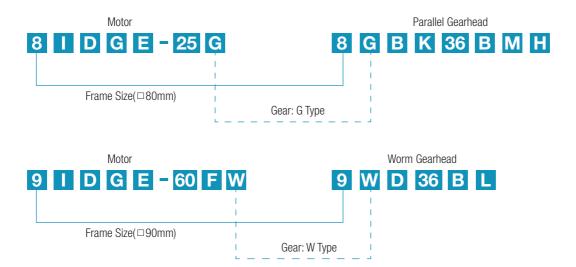
A Information

Product Coding System

Assembly of Motor and Gearhead

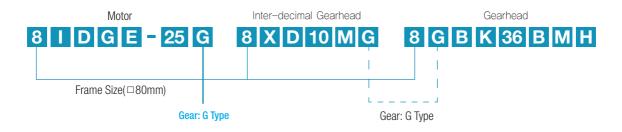
Motor + Gearhead

As shown in the following scheme, motor and gearhead which have same frame size and gear type could be assembled.



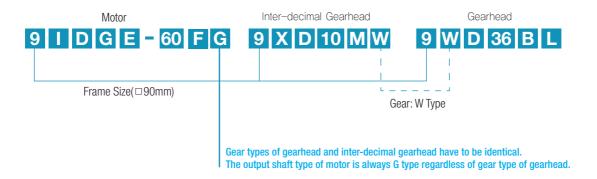
Motor + Inter-decimal Gearhead + Gearhead

• When using an inter-decimal gearhead together, give attention to the gear types of motor, gearhead and inter-decimal gearhead.



• When attaching inter-decimal gearhead, the output shaft type of the motor is always G Type.

For example, when using P/H/W/WH type gearhead, only the gear type of inter-decimal gearhead is identical with attached gearhead and the output shaft type of the motor is G type. (Refer to the scheme below.)



Contents

A Information

- A-01 Product Coding System
- **A-04** Products Lineup
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B AC Motors

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- B-138 Clutch & Brake Motor
- B-154 Torque Motor
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 - B-178 Speed Control Induction Motor
 - B-212 Speed Control Reversible Motor
 - B-240 Speed Control E.M. Brake Motor
 - B-266 Speed Control Clutch & Brake Motor

C DC Motors

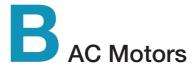
- C-01 Technical Data of DC Motor
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D Gearheads

- **D-01** Technical Data of Gearhead
- **D-07** Parallel Gearhead
- **D-12** Worm Gearhead
- **D-14** Inter-decimal Gearhead

E Options

- **E-01** Mounting Plate
- **E-02** Extension Cable
- **E-03** Output Flange / Output Shaft



Technical Data of AC Motor

Definition of Motor

Motor is a machine to get a driving force for rotation or straight movement by converting the electrical energy into mechanical energy and the light-weighted motor which enables to select the model suitable for the load, has less noise and vibration as well as no exhaust pollution.

Features of DKM AC Motor

DKM AC geared motor was developed first in Korea in 1987 and has been used in a good reputation throughout the whole areas of domestic/overseas industry up to know. Our AC geared motor is proud of various and wide range of specification which satisfies various electrical requirements from all over the world.

Various and Abundant Models

- There are various and abundant models in frame size covering □ 60/70/80/90mm such as Induction Motor, 2 Pole Motor, Reversible Motor, E.M. Brake Motor, Clutch & Brake Motor, Torque Motor and Speed Control Motor.
- For use voltage, we have various voltage specification covering all areas in the globe: 100V 50/60Hz(Japan), 200V 50/60Hz(Japan), 110V 60Hz(Taiwan), 220V 60Hz(Korea, Taiwan), 115V 60Hz(North America), 230V 50Hz(Europe, Oceania), 220V/240V 50Hz(South-East Asia)

Low Noise and Low Vibration

- Due to the enhancement of quality standard such as places and conditions for motors to use, the low noise and low vibration are required.
- To satisfy theses conditions, we employed high precision of gear processing and skiving cutting method and we are making a rotor which is the root cause of vibration by verifying with balance machine for low noise and low vibration.

Easy to Use

- Easy and safe to use as motor and gearhead are sold according to the requirements so that it can be designed and manufactured optimally.
- It is easy to drive to get a driving force by connecting capacitor to the commercial power available to be used anywhere and anytime. As capacitor is not needed for three phase power, it is available to get a driving force easily by connecting three phase power to the motor directly.

Just-In-Time System

• Just-In-Time system is available in DKM Motor Co., Ltd. for the best delivery system. DKM realized user's satisfaction with the world best delivery system.

Types of Motor

Classification by Power

- AC motor: A motor operated by AC power. For example, inductive motor, synchronous motor, AC commutator motor etc.
 - 1) Single Phase Motor
 - Single phase power is composed of one phase as commercial power for home.
 - As power itself does not make motor rotate, capacitor is connected to auxiliary coil to start.

2) Three Phase Motor

- Three phase motor stands for electrical power and it is consisted of three electrical sources with a phase offset of 120° in voltage.
- Connect the power to motor to start and the rotor will start to run easily.
- The efficiency of motor is high and the starting torque is relatively big.
- DC motor: A motor which rotates by supplying the direct current to the armature. The torque generated by placing the coil between magnetic poles N and S and applying the current to this coil rotates the motor. Whenever this coil passes the neutral shaft, it turns the direction of current reversely and rotates continuously



Classification by Function

Motor with Constant Speed

- 1) Induction Motor: An induction motor is a type of AC motor where power is supplied to the rotor by means of electromagnetic induction.

 These motors are widely used in industrial drives, particularly polyphase induction motors, because they are rugged and have no brushes.

 Their speed is determined by the frequency of the supply current, so they are most widely used in constant-speed applications, although variable speed versions, using variable frequency drives are becoming more common.
- 2) Reversible Motor: A kind of induction motor and a motor having the same characteristic in any direction such as left turn or right turn. In principle, it is same as induction motor but there is no relation of main coil and auxiliary coil like general induction motor in order to stand frequent normal/reverse rotation and get a big starting torque.

Electromagnetic Brake Motor

It is a motor embedded with fail-safe electromagnetic brake. Perfect braking enables to get a staying power. Brake runs only when the power is shutdown, so this is suitable as a brake for safe use.

* DKM has 'A Type' electronic brake motor which runs when the power is applied. (Customized specification)

Clutch & Brake Motor

DKM Clutch & Brake motor is equipped with Clutch & Brake mechanism available to be used with gearhead. As the continuously rotating induction motor and Clutch & Brake are combined, this can be used for frequent start/stop, position control, index operation and relative value feeding operation etc.

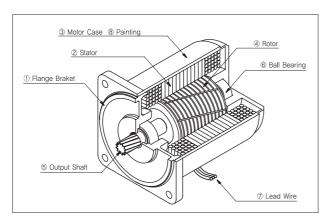
Torque Motor

DKM torque motor has big starting torque and sloping characteristics. It runs safely over the whole area of rotation speed-torque characteristics. (Torque is highest at zero speed and decreases steadily with increasing speed.) With these characteristics, this can be used for more application as a winding or tension motor.

Speed Control Motor

User can easily set and adjust the motor speed. There are three kinds of speed controller for AC speed motors. Select the best system depending upon your application.

Structure of AC Motor



1 Flange Bracket

Die-cast aluminum bracket is press-fitted into the motor case. The flange and the housing are a single body type which plays an important part to attach the motor alone or combine the gearhead.

2 Stator

This is comprised of a stator core made from laminated silicon/steel plates, a polyester-coated copper coil and insulation film. The roles are to generate magnetic field, form the rotation and run the rotor.

3 Motor Case

Die-cast aluminum with a machined finish inside

4 Rotor

It is comprised of laminated silicon/steel plates with die-cast aluminum. Rotor plays the part to change the electric energy to mechanical energy and transfer it to outside through shaft.

⑤ Output Shaft

There are round type shaft, D-cut type shaft, key type shaft which are for using by motor itself and gear type shaft (pinion shaft) which is for attaching gearhead. It is made by S45C with a machined finish.

6 Ball Bearing

It ensures that the rotor remains at the right position for the reliability and fast rotational motion.

(7) Lead Wire

Lead wires with heat-resistant polyethylene coating

8 Painting

Backed finish of acrylic resin and melamine resin with beautiful look



Technical Data of AC Motor

Temperature Rise of AC Motor

Temperature Rise

- In operation of motor, the loss inside of motor is changed to heat causing the motor's temperature to rise.
 - Induction Motor (for continuous duty) reaches the saturation point of temperature rise in about two or three hours of operation and temperature stabilizes.
 - Reversible Motor (30 minutes rating) reaches their limit of temperature rise in about 30 minutes of operation. If operation continues as it is, the temperature will increase further.

Measuring Temperature Rise

- DKM uses the following methods for temperature measurement and for the determination of a motor's allowable temperature rise.
 - Thermometer Method: The temperature rise at which the temperature rise becomes saturated during motor operation is measured by using a thermometer or thermocouple installed in the center of the motor case. The temperature rise is the difference between the ambient temperature and measured temperature during motor operation.
 - Resistance Method: This is the way of measuring the winding temperature according to the change in resistance value. The motor's winding resistance and ambient temperature is measured by using a resistance meter and thermostat.

Overheating Protection Device

• In case of that a running motor locks due to overload or the input current increases due to any reason or ambient temperature increases suddenly, the motor's temperature rises abruptly. If this state continues, the insulation performance may deteriorate and, in extreme cases, it may cause a fire. To avoid this case, DKM employs the following overheating protection devices.

• Thermal Protector (TP)

DKM installs the thermal protector for overheating protection of the motor. The TP employs a bimetal contact with pure silver used in the contacts. Pure silver has the lowest electrical resistance of all materials and has thermal conductivity second only to copper. (Operating Temperature: Open $120^{\circ}\pm5^{\circ}$) / Close $90^{\circ}\pm5^{\circ}$)

· Impedance Protection

Impedance-protected motor has higher impedance in the motor windings so although the motor locks, the increase in input current is minimized and temperature will not rise.

Insulation Class

DKM Motor's insulation class is B class. Insulation class is according to heat-resistance class. According to JIS C4003(IEC60085),
it is defined as below. It is also available to use other materials for some particular insulation class according to operating conditions or user's request.
(Customized specification)

Insulation Class	Max. Permissible Temp.
Υ	90℃
Α	105℃
E	120℃
В	130℃
F	155℃
Н	180℃

FAN

• It is available to attach two kinds of fan to the DKM's motor; 'General Fan (F type)' and 'Powerful Fan (F2 type)'.
General fan is attached to motor shaft rotating in same speed as that of motor shaft. (1,800r/min in 60Hz, 1,500r/min in 50Hz) Powerful fan makes powerful cooling performance rotating in high speed regardless of motor shaft speed. (3,200r/min in 60Hz. Temperature reducing over 10°C is available comparing general fan.)

DKM employs general fan to the motors with continuous speed and employs powerful fan by customers' special order to the continuous speed's motor. But in case of speed control motor in which speed control is needed, powerful fan is employed basically because there is little cooling effect in low speed if general fan is used.



(i) Equipment Protection Structure (IP Code)

- The IP code is one of the equipment protection structures and indicates the dust-resistance and waterproofing degrees of protection for the equipment.
- The code consists of the first number and the second number.



- "X" is used when one of the two protection classes is not specified in the name. (e.g. IPX5, IP4X)
- Meanings of IP code and testing conditions are as below;

1) The Classification of Dustproof

IP Code	Protection Specifications for Dustproof								
First Number	Protection Level	Test Condition							
IP0□	None	None							
IP1 a	Protection against approach by hands	Solid objects with a diameter of 50mm or more do not enter.							
IP2□	Protection against approach by fingers	Solid objects with a diameter of 12mm or more do not enter.							
IP3□	Protection against tips of tools etc.	Solid objects with a diameter of 2.5mm or more do not enter.							
IP4¤	Protection against ingress of wires etc.	Solid objects with a diameter of 1.0mm or more do not enter.							
IP5□	Protection against powdery dust	Powdery dust that may inhibit normal operation does not enter.							
IP6□	Completely dustproof design	Cannot be penetrated by powdery dust.							

2) The Classification of Waterproof

IP Code	Protection Specifications for Waterproof									
Second Number	Protection Level	Test Condition								
IP□0	None	None								
IP=1	Protection against water drops falling vertically	Water drops at a rate of 3 to 5L/min. for 10 minutes from a height of 200mm								
IP¤2	Protection against water drops from directions within a range of 15° relative to the vertical plane	Water drops at a rate of 3 to 5L/min. for 10 minutes from directions within 15° from a height of 200mm								
IP□3	Protection against raindrops from directions within a range of 60° relative to the vertical plane	Sprayed water at a rate of 10L/min. for 10 minutes from directions within 60° from a height of 200mm								
IP=4	Protection against ingress of splashes from all directions	Sprayed water at a rate of 10L/min. for 10 minutes from all directions at a distance of 300 to 500mm								
IP□5	Protection against water jet from all directions	Sprayed water jet of 30kPa at a rate of 12.5L/min. for 3 minutes from all directions at a distance of 3m								
IP□6	Protection against strong water jet such as ocean waves	Sprayed water jet of 100kPa at a rate of 100L/min. for 3 minutes from all directions at a distance of 3m								
IP¤7	Usable after immersion in water under specified conditions	Immersion to a depth of 1m for 30 minutes								
IP□8	Usable under water	Determined through cooperation between user and manufacturer.								

• The IP code of DKM's motor is indicated in the name plate (motor label).

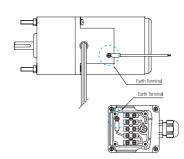
Earth Method

Lead Wire Type

As shown in the figure, connect the earth wire to the earth hole in the side of the motor.
 Screw the earth wire to the earth hole. (Sequence: earth hole → washer → earth wire → screw bolt)

Terminal Box Type

Connect the earth wire to the earth terminal in the terminal box.





2 Pole Motor



Index	
2 Pole Motor 15W (□80mm)	B-49
2 Pole Motor 25W (□80mm)	B-51
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2 Pole Motor 90W (□90mm)	B-57
2 Pole Motor 120W (□90mm)	B-59
2 Pole Motor 150W (□90mm)	B-61
2 Pole Motor 200W (□90mm)	B-63



2 Pole Motor 15W(□80mm)



Motor Specification

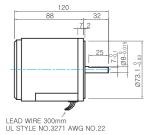
M	Model		Voltage	Frequency	Poles	Duty	a =			Capacitor				
	D-Cut Type Shaft	Output	Voltage	Hz	ruies	Duty	Starting Torque kgfcm N.m		N.m Speed	Current	Torque	μF / VAC		
Lead Wire Type	Terminal Box Type								r/min	Α	kgfcm N.m	μ. γ τ τ τ τ		
8IDDA-15-A	8IDDA-15-AT	15	1ø110	60	2	Cont.	0.60	0.060	3250	0.41	0.46 0.046	6.0 / 250		
8IDDD-15-A	8IDDD-15-AT	15	1ø220	60	2	Cont.	0.60	0.060	3200	0.26	0.46 0.046	2.0 / 250		
8IDDE-15-A	8IDDE-15-AT	15	1ø220	50	50	FO		0	0.60	0.060	2550	0.28	0.60 0.060	0.0 / 450
9IDDE-19-A	SIDDE-15-AT	15	1ø240	50	2	Cont.	0.80	0.080	2550	0.30	0.70 0.070	2.0 / 450		
8IDDG-15-A	8IDDG-15-AT	15	3ø220	50	2	Cont	1.30	0.130	2600	0.27	0.60 0.060			
61DDG-15-A	61DDG-15-A1	15	30220	60	2	Cont.	1.20	0.120	3200	0.25	0.46 0.046	_		

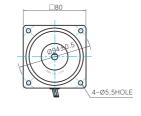
¹⁾ Enter the phase & voltage code in the box (\Box) within the motor model name.

Dimensions

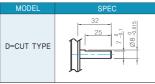
LEAD WIRE TYPE

● MOTOR MODEL: 8IDD □-15-A (NO FAN)



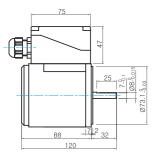


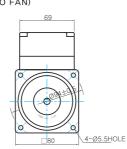
MOTOR OUTPUT SHAFT



TERMINAL BOX TYPE

● MOTOR MODEL: 8IDD =-15-AT (NO FAN)





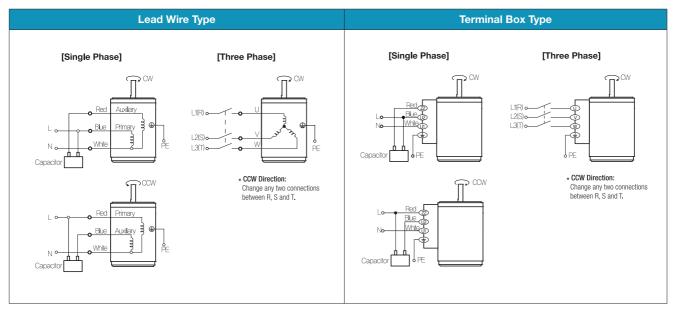
PART	WEIGHT(Kg)
MOTOR	1.6

²⁾ All models contain a built-in thermal protector.





(iii) Connection Diagrams



- 1) The direction of motor rotation is as viewed from the shaft end of the motor.
- 2) CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- 3) Change the direction of single phase motor rotation only after bringing the motor to a stop. If an attempt is made to change the direction of rotation while the motor is rotating, the motor may ignore the reversing command or change its direction after some delay.



2 Pole Motor 25W(□80mm)



Motor Specification

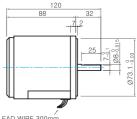
M	odel	Output	Voltage	Frequency	Poles	Duty						Rated L	oad.	Capacitor
	D-Cut Type Shaft	W	Voltage	Hz	rules	July	Kgtcm N.M		Speed	Current	Torque	μF / VAC		
Lead Wire Type	Terminal Box Type								r/min	Α	kgfcm N.m	, , , , , , , , , , , , , , , , , , ,		
8IDDA-25-A	8IDDA-25-AT	25	1ø110	60	2	Cont.	0.80	0.080	3200	0.44	0.76 0.076	6.0 / 250		
8IDDD-25-A	8IDDD-25-AT	25	1ø220	60	2	Cont.	0.80	0.080	3200	0.31	0.77 0.077	2.5 / 250		
8IDDE-25-A	8IDDE-25-AT	25	1ø220	50	50	2	0	1.00	0.100	2500	0.33	1.00 0.100	2.5 / 450	
61DDE-25-A	91DDE-23-A1	25	1ø240			2	Cont.	1.20	0.120	2500	0.36	1.10 0.110	7 2.5 / 450	
8IDDG-25-A	8IDDG-25-AT	25	2 ~ 220	50	50 2		1.40	0.140	2600	0.28	0.78 0.078	3		
61DDG-25-A	61DDG-25-A1	25	3ø220	60] ~	Cont.	1.30	0.130	3200	0.26	0.77 0.077	_		

¹⁾ Enter the phase & voltage code in the box (\square) within the motor model name.

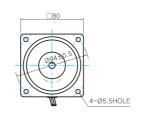
Dimensions

LEAD WIRE TYPE

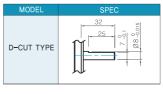
● MOTOR MODEL: 8IDD = -25-A (NO FAN)



LEAD WIRE 300mm UL STYLE NO.3271 AWG NO.22

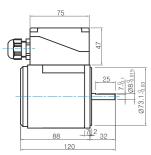


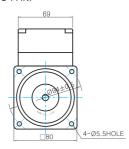
MOTOR OUTPUT SHAFT



TERMINAL BOX TYPE

● MOTOR MODEL: 8IDD = -25-AT (NO FAN)





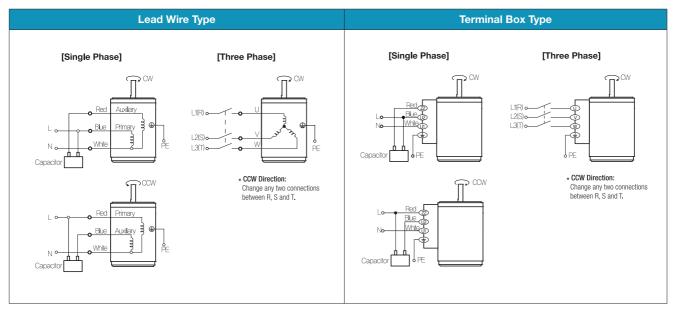
PART	WEIGHT(Kg)
MOTOR	1.6

²⁾ All models contain a built-in thermal protector.





Connection Diagrams



- 1) The direction of motor rotation is as viewed from the shaft end of the motor.
- 2) CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- 3) Change the direction of single phase motor rotation only after bringing the motor to a stop. If an attempt is made to change the direction of rotation while the motor is rotating, the motor may ignore the reversing command or change its direction after some delay.



2 Pole Motor 40W(□90mm)



Motor Specification

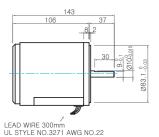
Mo	odel	Output	Valtage	Eroguanav	Doloo	Duty				Rated L	oad		Capacitor
	: D-Cut Type Shaft : Key Type Shaft	Output Volta W V		Frequency Hz	Poles	Duty	Starting kgfcm	Torque N.m	Speed		Torqu		uF / VAC
Lead Wire Type	Terminal Box Type								r/min	Α	kgfcm l	N.m	j., 7 77.0
9IDDA-40-A	9IDDA-40-AT	40	1ø110	60	2	Cont.	1.60	0.160	3200	1.20	1.30 0	.130	12.0 / 250
9IDDD-40-A	9IDDD-40-AT	40	1ø220	60	2	Cont.	1.60	0.160	3200	0.45	1.30 0	.130	4.0 / 250
9IDDE-40-A	9IDDE-40-AT	40	1ø220	50	2	Cont.	1.60	0.160	2650	0.54	1.50 0	.150	4.0 / 450
9IDDE-40-A	9IDDE-40-AT	40	1ø240	50	~	Cont.	1.80	0.180	2000	0.55	1.70 0	.170	4.0 / 450
9IDDG-40-A	9IDDG-40-AT	40	3ø220	50	2	Cont	4.00	0.400	2700	0.55	1.45 0	.145	
91DDG-40-A	91DDG-40-A1	40	30220	60	-	Cont.	3.00	0.300	3300	0.40	1.20 0	.120	_
			2 ~ 200	50	2	0	3.00	0.300	2700	0.32	1.45 0	.145	
			3ø380	60	2	Cont.	2.80	0.280	3300	0.23	1.20 0	.120	
			0 = 400	50		0	3.20	0.320	2750	0.37	1.45 0	.145	
01001/ 40 4	01001/ 40 47	40	3ø400	60	2	Cont.	3.00	0.300	3300	0.26	1.40 0	.140	
9IDDK-40-A	9IDDK-40-AT	40	0 = 415	50		0	3.40	0.340	2750	0.41	1.60 0	.160	_
			3ø415	60	2	Cont.	3.20	0.320	3350	0.27	1.30 0	.130	
			0 :: 440	50			3.70	0.370	2750	0.48	2.00 0	.200	
			3ø440	60	2	Cont.	3.50	0.350	3350	0.29	1.70 0	.170	

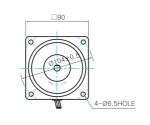
¹⁾ Enter the phase & voltage code in the box (\Box) within the motor model name.

Dimensions

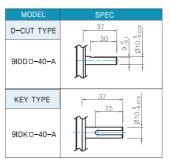
LEAD WIRE TYPE

● MOTOR MODEL: 9IDD□-40-A (NO FAN)

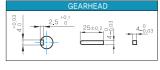




MOTOR OUTPUT SHAFT

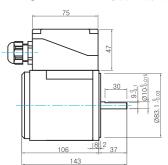


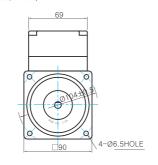
KEY SPEC



TERMINAL BOX TYPE

● MOTOR MODEL: 9IDD = -40-AT (NO FAN)





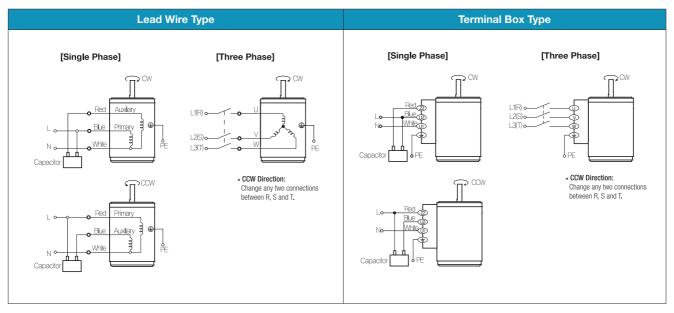
PART	WEIGHT(Kg)
MOTOR	2.4

²⁾ All models contain a built-in thermal protector.

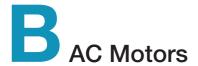




(iii) Connection Diagrams



- 1) The direction of motor rotation is as viewed from the shaft end of the motor.
- 2) CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- 3) Change the direction of single phase motor rotation only after bringing the motor to a stop. If an attempt is made to change the direction of rotation while the motor is rotating, the motor may ignore the reversing command or change its direction after some delay.



2 Pole Motor 60W(□90mm)

60W 2 Pole Motor 60W(□90mm)

Motor Specification

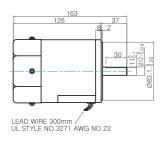
Mo	odel	Output	Voltago	Frequency	Polos	Duty	5	_		Capacitor		
	C): D-Cut Type Shaft C): Key Type Shaft	W	Voltage	Hz	rules	Duty	Starting kgfcm	Torque N.m	Speed		Torque	uF / VAC
Lead Wire Type	Terminal Box Type								r/min	Α	kgfcm N.m	μι γ νλο
9IDDA-60F-A	9IDDA-60F-AT	60	1ø110	60	2	Cont.	2.00	0.200	3200	1.20	1.84 0.184	16.0 / 250
9IDDD-60F-A	9IDDD-60F-AT	60	1ø220	60	2	Cont.	2.00	0.200	3200	0.65	1.84 0.184	5.0 / 450
AIDDE COE A	OIDDE COE AT	00	1ø220	50	0	2 Cont.	2.40	0.240	0700	0.89	2.20 0.220	F 0 / 4F0
9IDDE-60F-A	9IDDE-60F-AT	60	1ø240	50			Cont.	2.80	0.280	2700	1.10	2.40 0.240
01000 005 4	01000 005 47	00	0 000	50	0	0 1	8.00	0.800	2750	0.59	2.20 0.220	
9IDDG-60F-A	9IDDG-60F-AT	60	3ø220	60	2	Cont.	6.00	0.600	3300	0.41	1.80 0.180	_
			0000	50	0	0	8.00	0.800	2700	0.34	2.20 0.220	
			3ø380	60	2	Cont.	6.00	0.600	3250	0.26	1.80 0.180	
			0 :: 400	50	0	0	9.00	0.900	2700	0.40	2.40 0.240	
		00	3ø400	60	2	Cont.	7.00	0.700	3250	0.27	2.00 0.200	
9IDDK-60F-A	9IDDK-60F-AT	60	0 :: 445	50		0	10.00	1.000	2750	0.46	2.20 0.220	-
			3ø415	60	2	Cont.	8.00	0.800	3300	0.29	1.80 0.180	
			0 :: 440	50	0	0	12.00	1.200	2800	0.53	2.20 0.220	
			3ø440	60	2	Cont.	10.00	1.000	3350	0.31	1.80 0.180	

¹⁾ Enter the phase & voltage code in the box (\Box) within the motor model name.

Dimensions

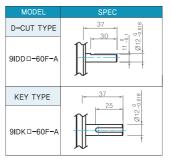
LEAD WIRE TYPE

● MOTOR MODEL: 9IDD□-60F-A (GENERAL FAN)

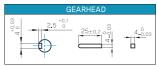




MOTOR OUTPUT SHAFT

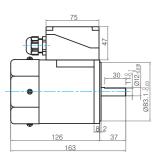


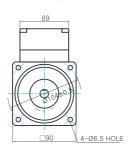




TERMINAL BOX TYPE

● MOTOR MODEL: 9IDD□-60F-AT (GENERAL FAN)





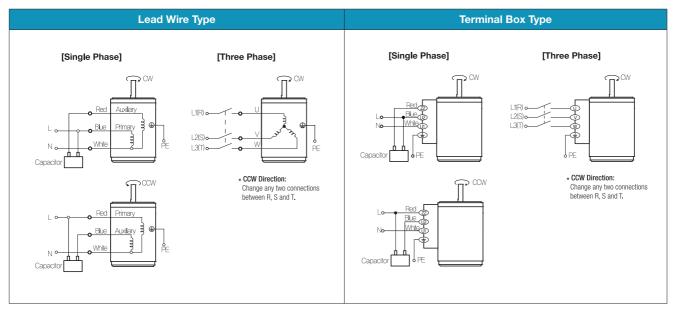
PART	WEIGHT(Kg)
MOTOR	2.6

All models contain a built-in thermal protector.





(iii) Connection Diagrams



- 1) The direction of motor rotation is as viewed from the shaft end of the motor.
- 2) CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- 3) Change the direction of single phase motor rotation only after bringing the motor to a stop. If an attempt is made to change the direction of rotation while the motor is rotating, the motor may ignore the reversing command or change its direction after some delay.



2 Pole Motor 90W(□90mm)

90W(□90mm)

Motor Specification

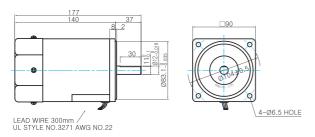
Model		Output	Valtage	Eroguenov	Doloo Dub			_		Consoiter		
	T): D-Cut Type Shaft T): Key Type Shaft	Output	Voltage	Frequency Hz	Poles	Duty	Starting kgfcm	Torque N.m	Speed	Current	Torque	Capacitor uF / VAC
Lead Wire Type	Terminal Box Type								r/min	Α	kgfcm N.m	μι / •/ΑΟ
9IDDA-90F-A	9IDDA-90F-AT	90	1ø110	60	2	Cont.	2.60	0.260	3200	1.80	2.80 0.280	20.0 / 250
9IDDD-90F-A	9IDDD-90F-AT	90	1ø220	60	2	Cont.	2.60	0.260	3200	1.00	2.80 0.280	6.0 / 450
OIDDE OOF A	01005 005 4 01005 005 47	90	1ø220	50	2	Cont.	3.00	0.300	2600	0.89	3.40 0.340	6.0 / 450
9IDDE-90F-AT	9IDDE-90F-AI		1ø240	50	2		3.60	0.360		1.00	3.80 0.380	
9IDDG-90F-A 9IDDG-9	OIDDO OOF AT	90	3ø220	50	2 Cont.	0	10.00	1.000	2750	0.80	3.20 0.320	_
	9IDDG-90F-A1			60		Cont.	8.00	0.800	3300	0.56	2.80 0.280	
			2 ~ 200	50	2	0	10.00	1.000	2750	0.43	3.20 0.320	
			3ø380	60	2	Cont.	8.00	0.800	3300	0.34	2.70 0.270	
			0 = 400	50	_	0	11.00	1.100	2750	0.50	3.40 0.340	
01001/ 005 4	01001/ 005 47	00	3ø400	60	2	Cont.	9.00	0.900	3300	0.36	3.00 0.300	
9IDDK-90F-A	9IDDK-90F-AT	90	0 = 415	50	_	0	12.00	1.200	2800	0.57	3.60 0.360	-
			3ø415	60	2	Cont.	10.00	1.000	3350	0.38	3.30 0.330	
			0 :: 440	50	_	0	14.00	1.400	2800	0.67	3.80 0.380	
			3ø440	60	2	Cont.	12.00	1.200	3350	0.40	3.20 0.320	

¹⁾ Enter the phase & voltage code in the box (\Box) within the motor model name.

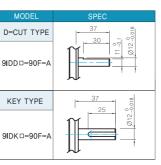
Dimensions

LEAD WIRE TYPE

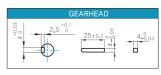
● MOTOR MODEL: 9IDD□-90F-A (GENERAL FAN)



MOTOR OUTPUT SHAFT

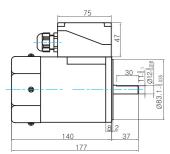


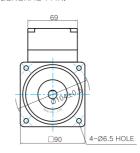
KEY SPEC



TERMINAL BOX TYPE

● MOTOR MODEL: 9IDD□-90F-AT (GENERAL FAN)





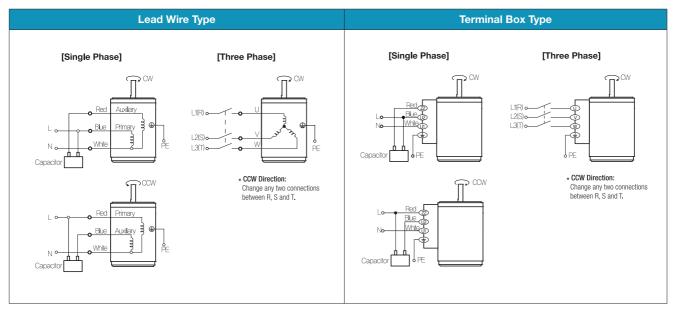
PART	WEIGHT(Kg)
MOTOR	2,6

²⁾ All models contain a built-in thermal protector.

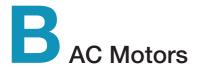




() Connection Diagrams



- 1) The direction of motor rotation is as viewed from the shaft end of the motor.
- 2) CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- 3) Change the direction of single phase motor rotation only after bringing the motor to a stop. If an attempt is made to change the direction of rotation while the motor is rotating, the motor may ignore the reversing command or change its direction after some delay.



2 Pole Motor 120W(□90mm)

120W 2 Pole Motor 120W(90mm)

Motor Specification

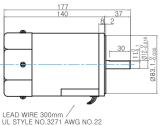
Model		Output	Voltage	Frequency	Poles	Duty	A: 11	_		Capacitor		
): D-Cut Type Shaft): Key Type Shaft	W	Voltage	Hz	rules	Duty	Starting kgfcm	Torque N.m	Speed	Current	Torque	uF / VAC
Lead Wire Type	Terminal Box Type								r/min	Α	kgfcm N.m	μι γ τγιο
9IDDA-120F-A	9IDDA-120F-AT	120	1ø110	60	2	Cont.	3.00	0.300	3100	2.40	3.80 0.380	25.0 / 250
9IDDD-120F-A	9IDDD-120F-AT	120	1ø220	60	2	Cont.	3.00	0.300	3100	1.40	3.80 0.380	6.5 / 450
01DDE 400E A	9IDDE-120F-AT	120	1ø220	50	2	Cont.	3.20	0.320	2500	1.20	4.70 0.470	6.5 / 450
9IDDE-120F-A		120	1ø240	50			3.80	0.380	2500	1.40	5.20 0.520	
9IDDG-120F-AT	01DD0 400E AT	120	3ø220	50	2 Cont.	Cont	12.00	1.200	2650	0.82	4.45 0.445	_
	120	30220	60		Z COIII.	10.00	1.000	3250	0.60	3.60 0.360		
		3ø380	50	2	Cont.	12.00	1.200	2650	0.46	4.60 0.460		
			30300	60	2	Cont.	10.00	1.000	3200	0.35	3.65 0.365	
			2 ~ 400	50	2	Cont	13.00	1.300	2700	0.53	4.40 0.440	
OIDDK 400E A	OIDDK 400E AT	100	3ø400	60	2	Cont.	11.00	1.100	3200	0.38	3.85 0.385	
9IDDK-120F-A	9IDDK-120F-AT	120	0 ~ 415	50	0	0	14.00	1.400	2700	0.60	4.60 0.460	-
			3ø415	60	2	Cont.	12.00	1.200	3250	0.41	3.65 0.365	
			2 = 440	50	_	0	16.00	1.600	2750	0.68	4.30 0.430	
			3ø440	60	2	Cont.	14.00	1.400	3250	0.45	3.80 0.380	

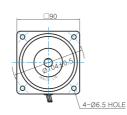
¹⁾ Enter the phase & voltage code in the box (\square) within the motor model name.

(iii) Dimensions

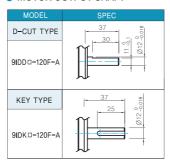
LEAD WIRE TYPE

● MOTOR MODEL: 9IDD □-120F-A (GENERAL FAN)

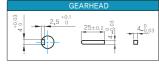




MOTOR OUTPUT SHAFT

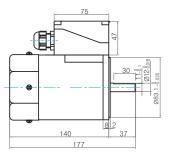


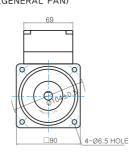
KEY SPEC



TERMINAL BOX TYPE

● MOTOR MODEL: 9IDD□-120F-AT (GENERAL FAN)





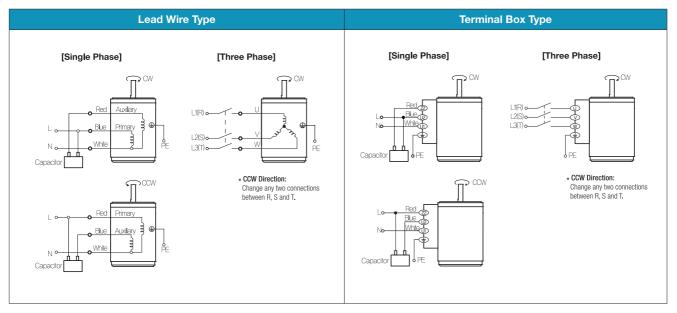
PART	WEIGHT(Kg)
MOTOR	3.0

²⁾ All models contain a built-in thermal protector.

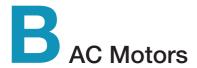




Connection Diagrams



- 1) The direction of motor rotation is as viewed from the shaft end of the motor.
- 2) CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- 3) Change the direction of single phase motor rotation only after bringing the motor to a stop. If an attempt is made to change the direction of rotation while the motor is rotating, the motor may ignore the reversing command or change its direction after some delay.



2 Pole Motor 150W(□90mm)

150W 2 Pole Motor 150W(□90mm)

Motor Specification

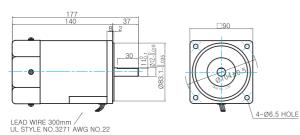
Model		Output	Voltage Er	Frequency	Poles Duty		_		Capacitor			
9IDD□-150F-A(T): D-Cut Type Shaft 9IDK□-150F-A(T): Key Type Shaft		W	Voltage	Hz	Fules	Duty	Starting kgfcm	Torque N.m	Speed	Current	Torque	uF / VAC
Lead Wire Type	Terminal Box Type		112						r/min	Α	kgfcm N.m	m / V/C
9IDDG-150F-A	OG-150F-A 9IDDG-150F-AT	150	3ø220	50	2	Cont.	14.00	1.400	2650	1.40	5.60 0.560	_
9100G-130F-A 9100G-130F-	91DDG-130F-A1	130	30220	60			12.00	1.200	3250	0.86	4.60 0.460	
			3ø380	50	2	2 Cont.	1.40	0.140	2600	0.52	5.70 0.570	
				60			1.20	0.120	3150	0.46	4.70 0.470	
			3ø400	50	2	2 Cont.	1.50	0.150	2600	0.60	5.90 0.590	
9IDDK-150F-A	9IDDK-150F-AT	150		60			1.30	0.130	3200	0.46	4.90 0.490	
9100K-150F-A	9IDDK-150F-A1		3ø415	50	2	Cont	1.60	0.160	2700	0.60	5.60 0.560] _
			39415	60		Cont.	1.40	0.140	3200	0.46	4.60 0.460	
			3ø440	50	2	Cont.	1.80	0.180	2700	0.68	5.80 0.580	
				60	7 2	Cont.	1.60	0.160	3250	0.47	4.80 0.480	

¹⁾ Enter the phase & voltage code in the box (\square) within the motor model name.

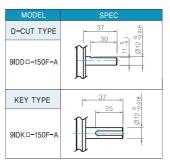
Dimensions

LEAD WIRE TYPE

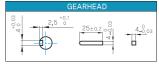
● MOTOR MODEL: 9IDD = -150F-A (GENERAL FAN)



MOTOR OUTPUT SHAFT

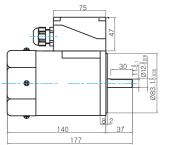


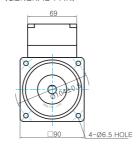
KEY SPEC



TERMINAL BOX TYPE

• MOTOR MODEL: 9IDD -150F-AT (GENERAL FAN)





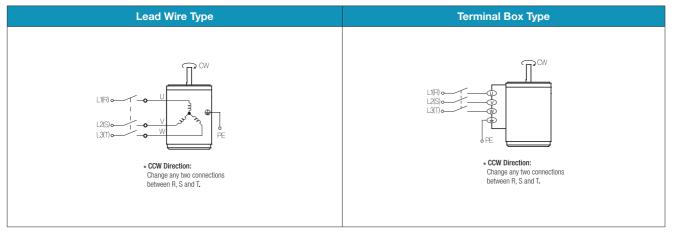
PART	WEIGHT(Kg)
MOTOR	3.0

²⁾ All models contain a built-in thermal protector.

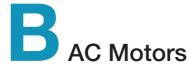




(iii) Connection Diagrams



- 1) The direction of motor rotation is as viewed from the shaft end of the motor.
- 2) CW represents the clockwise direction, while CCW represents the counterclockwise direction.



2 Pole Motor 200W(□90mm)

200W 2 Pole Motor 200W(□90mm)

(iii) Motor Specification

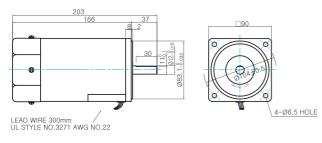
Model		Output	Voltage	Frequency	Poles	Duty	a –			Capacitor		
9IDD□-200F-A(T): D-Cut Type Shaft 9IDK□-200F-A(T): Key Type Shaft		W	Voltage	Hz	1 Oles	Duty	Starting kgfcm		Speed	Current	Torque	uF / VAC
Lead Wire Type	Terminal Box Type								r/min	Α	kgfcm N.m	μι 7 Υ ΑΟ
9IDDG-200F-A	9IDDG-200F-AT	200	3ø220	50	2	Cont.	20.00	2.000	2700	1.30	7.30 0.730	
9100G-200F-A	9IDDG-200F-AT	200	30220	60		COIII.	16.00	1,600	3200	0.90	6.10 0.610] -
			3ø380	50	2	Cont.	19.00	1.900	2700	0.70	7.40 0.740	
9IDDK-200F-A	9IDDK-200F-AT	200	30300	60		COIII.	16.00	1,600	3250	0.52	6.00 0.600] _
9IDDK-200F-A	91DDK-200F-A1	200	3ø400	50	2	Cont.	20.00	2.000	2700	0.72	7.60 0.760	
			3 9 4 0 0	60		Cont.	17.00	1.700	3250	0.57	6.20 0.620	

¹⁾ Enter the phase & voltage code in the box (\Box) within the motor model name.

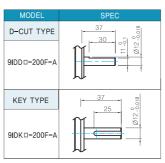
Dimensions

LEAD WIRE TYPE

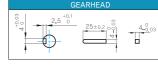
● MOTOR MODEL: 9IDD □-200F-A (GENERAL FAN)



MOTOR OUTPUT SHAFT

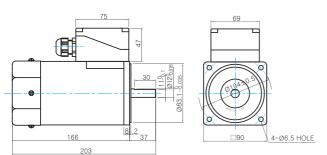


KEY SPEC



TERMINAL BOX TYPE

● MOTOR MODEL: 9IDD □-200F-AT (GENERAL FAN)



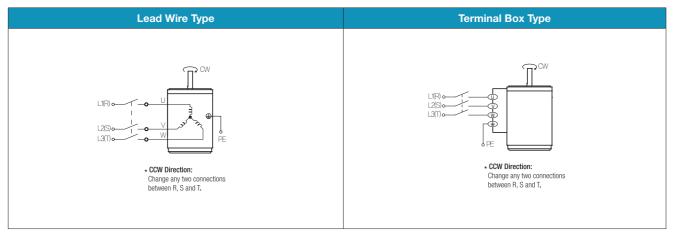
PART	WEIGHT(Kg)
MOTOR	3.8

²⁾ All models contain a built-in thermal protector.





(iii) Connection Diagrams



- 1) The direction of motor rotation is as viewed from the shaft end of the motor.
- 2) CW represents the clockwise direction, while CCW represents the counterclockwise direction.



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D-07 Parallel Gearhead

D-12 Worm Gearhead

D-14 Inter-decimal Gearhead

Options

E-01 Mounting Plate

E-02 Extension Cable

E-03 Output Flange / Output Shaft



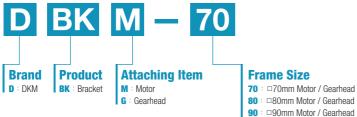
Mounting Plate

Mounting Plate

It enables motor/gearhead to be mounted on installation place.

There are mounting plates of frame size □70/80/90mm for motor and gearhead.

(iii) Product Code

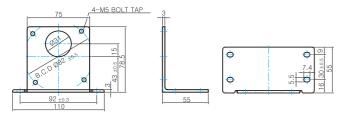




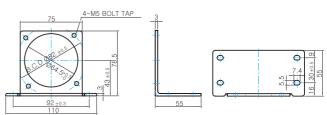
Dimensions

For Frame Size □70mm

Model: DBKG-70

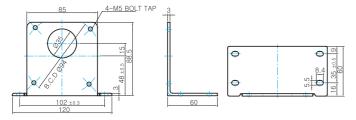


Model: DBKM-70

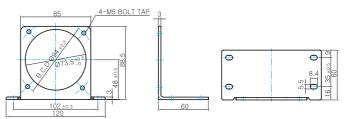


For Frame Size □80mm

Model: DBKG-80

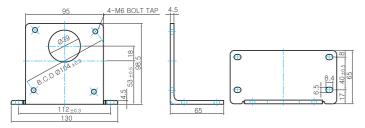


Model: DBKM-80

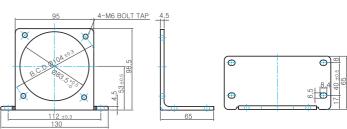


For Frame Size □90mm

Model: DBKG-90



■ Model: DBKM-90





Extension Cable

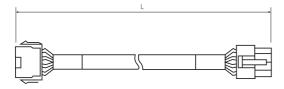
Extension Cable

This is for the connection between speed control motor and speed controller.

The basic length of extension cable is 0.3m. So if longer needed, please order the cable additionally. There are 0.5/1.0/1.5/2.0/3.0/5.0m extension cables.



(iii) Dimension



MODEL	Length of cable (L)
DEW-05	0.5m
DEW-10	1.0m
DEW-15	1.5m
DEW-20	2.0m
DEW-30	3.0m
DEW-50	5.0m



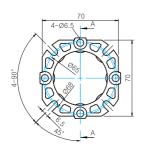
Output Flange / Output Shaft

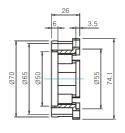
Output Flange

It is available to fix/install worm hollow type gearhead by attaching output flange to the gearhead.

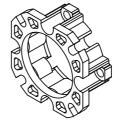
Dimensions

MODEL: WHG-030-F









Output Shaft

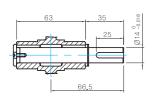
These are output shafts to be attached to worm hollow type gearhead.

There are unidirectional output shaft and bi-directional output shaft.

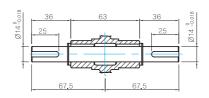


Dimensions

• Unidirectional MODEL: 15X92L



Bi-directional MODEL: 14X135L



KEY SPEC

